Congestion control and multipath routing in TCP/IP communication networks

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- Congestion control and network utility maximization
- Ongestion control with Markovian multipath routing
- Implementation issues

NUM model Steady state Network as an Optimizer

Framework

- Communication network G = (N, A)
- Set of sources S
- Source $s \in S$ transmits from origin o_s to destination d_s
- A single route connects o_s to d_s



Notation: $a \in s$ iff link a belongs to route used by source s

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TCP/IP Protocols

Route selection

Routing Information Protocol (RIP) slow timescale evolution (15-30 seconds)

Rate control

Transmission Control Protocol (TCP) fast timescale evolution (100-300 milliseconds)

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TCP – Congestion control

Sources adjust transmission rates in response to congestion higher congestion \Rightarrow smaller rates

- $(x_s)_{s \in S}$: source transmission rates [packets/sec]
- $(\lambda_a)_{a \in A}$: link congestion prices (loss pbb, queuing delay)

Decentralized algorithms

$$\begin{array}{lll} x_s^{t+1} &=& F_s(x_s^t, q_s^t) & (\text{source - transmission control protocol}) \\ \lambda_a^{t+1} &=& G_a(\lambda_a^t, y_a^t) & (\text{link - active queue management}) \end{array}$$

where

$$\begin{array}{l} q_s^t = \sum_{a \in s} \lambda_a^t \quad (\text{end-to-end route congestion}) \\ y_a^t = \sum_{s \ni a} x_s^t \quad (\text{aggregate rates on links}) \end{array}$$

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Example: TCP-Reno/DropTail-RED-REM

TCP-DropTail: control window AIMD (τ_s = round-trip time):

 $W_s^{t+\tau_s} = \begin{cases} W_s^t + 1 & \text{if } W_s^t \text{ packets are successfully transmitted} \\ \lceil W_s^t/2 \rceil & \text{one or more packets are lost (duplicate ack's)} \end{cases}$

A packet is transmitted successfully with probability

$$\pi_s^t = \prod_{a \in s} (1 - p_a^t)$$

RED-REM: loss probability on links controlled by AQM

$$p_a^t = \varphi_a(r_a^t)$$

as a function of the link's average queue length

$$r_a^{t+1} = (1 - \alpha_a)r_a^t + \alpha_a L_a^t$$

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Example: TCP-Reno/RED-REM



Figura: Loss probability $p_a = \varphi_a(r_a)$ as a function of average queue length

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Example: TCP-Reno/RED-REM

Congestion prices

$$\begin{array}{l} q_s^t & \triangleq & -\ln(\pi_s^t) \\ \lambda_a^t & \triangleq & -\ln(1-p_a^t) \end{array} \right\} \Rightarrow \boxed{q_s^t = \sum_{a \in s} \lambda_a^t}$$

The approximate equality

$$\mathbb{E}(W_s^{t+\tau_s}|W_s^t) \sim e^{-q_s^t W_s^t} (W_s^t+1) + (1 - e^{-q_s^t W_s^t}) \lceil W_s^t/2 \rceil$$

yields the following expected dynamics for rates $x_s^t = W_s^t / \tau_s$

$$\Rightarrow x_s^{t+1} = x_s^t + \frac{1}{2\tau_s} \left[e^{-\tau_s q_s^t x_s^t} \left(x_s^t + \frac{2}{\tau_s} \right) - x_s^t \right]$$

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$$\mathbb{E}(W^{t+\tau_s}_s|W^t_s) \sim e^{-q^t_s W^t_s}(W^t_s+1) + (1-e^{-q^t_s W^t_s}) \lceil W^t_s/2 \rceil$$

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yields the following expected dynamics for rates $x_s^t = W_s^t / \tau_s$

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Another example: TCP-Vegas

TCP-Vegas uses queueing delay as congestion measure

$$\lambda_a = rac{L_a}{c_a} = rac{ ext{queue length}}{ ext{queue capacity}}$$

A simple model for the dynamics

$$\begin{aligned} \lambda_a^{t+1} &= \left[\lambda_a^t + \frac{y_a^t}{c_a} - 1\right]_+ \\ x_s^{t+1} &= x_s^t + \frac{1}{(d_s + q_s^t)^2} \operatorname{sign}(\alpha_s d_s - x_s^t q_s^t). \end{aligned}$$

with

$$\alpha_s =$$
parameter of Vegas
 $d_s =$ round-trip propagation delay

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Network Utility Maximization

- Kelly, Maullo and Tan (1999) proposed an optimization-based model for distributed rate control in networks.
- Low, Srikant, etc. (1999-2002) showed that TCP congestion control algorithms solve implicitly an optimization problem.
- During last decade, the model has been used and extended to study the performance of wired and wireless networks.

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Steady state equations

$$egin{array}{rcl} x^{t+1}_s &=& F_s(x^t_s,q^t_s) & ({\sf TCP}\ -\ {\sf source}\ {\sf dynamics})\ \lambda^{t+1}_a &=& G_a(\lambda^t_a,y^t_a) & ({\sf AQM}\ -\ {\sf link}\ {\sf dynamics}) \end{array}$$

$$\begin{aligned} x_s &= F_s(x_s, q_s) \iff q_s = f_s(x_s) & \text{(decreasing)} \\ \lambda_a &= G_a(y_a, \lambda_a) \iff \lambda_a = \psi_a(y_a) & \text{(increasing)} \\ q_s &= \sum_{a \in s} \lambda_a \\ y_a &= \sum_{s \ni a} x_s \end{aligned}$$

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Example: TCP/REM steady state

$$q_s = f_s(x_s) \triangleq rac{1}{ au_s x_s} \ln(1 + rac{2}{ au_s x_s})$$

$$\left. \begin{array}{l} \rho_{a} = \varphi_{a}(r_{a}) \triangleq 1 - \exp(-\delta r_{a}) \\ r_{a} = \mathbb{E}(L_{a}) = \frac{y_{a}}{c_{a} - y_{a}} \end{array} \right\}$$

$$\lambda_{a} = \psi_{a}(y_{a}) \triangleq -\ln(1 - \varphi_{a}(\frac{y_{a}}{c_{a} - y_{a}})) = \delta \frac{y_{a}}{c_{a} - y_{a}}$$

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NUM model Steady state Network as an Optimizer

Steady state - primal optimality

$$\begin{cases} q_s = f_s(x_s) \\ \lambda_a = \psi_a(y_a) \\ q_s = \sum_{a \in s} \lambda_a \\ y_a = \sum_{s \ni a} x_s \end{cases}$$

$$f_s(x_s) = \sum_{a \in s} \lambda_a = \sum_{a \in s} \psi_a(y_a) = \sum_{a \in s} \psi_a(\sum_{s \ni a} x_s)$$

 \equiv optimal solution of strictly convex program

$$(P) \qquad \underbrace{\min_{x} \sum_{s \in S} F_s(x_s) + \sum_{a \in A} \Psi_a(\sum_{s \ni a} x_s)}_{F'_s(\cdot) = -f_s(\cdot)}$$
$$\Psi'_a(\cdot) = \psi_a(\cdot)$$

NUM model Steady state Network as an Optimizer

Steady state - primal optimality

$$\begin{cases} q_s = f_s(x_s) \\ \lambda_a = \psi_a(y_a) \\ q_s = \sum_{a \in s} \lambda_a \\ y_a = \sum_{s \ni a} x_s \end{cases}$$

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NUM model Steady state Network as an Optimizer

Steady state - dual optimality

Alternatively

$$\psi_a^{-1}(\lambda_a) = y_a = \sum_{s \ni a} x_s = \sum_{s \ni a} f_s^{-1}(q_s) = \sum_{s \ni a} f_s^{-1}(\sum_{a \in s} \lambda_a)$$

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$$\min_{\lambda} \sum_{a \in A} \Psi_a^*(\lambda_a) + \sum_{s \in S} F_s^*(\sum_{a \in s} \lambda_a)$$

NUM model Steady state Network as an Optimizer

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Congestion control & NUM Markovian NUM Implementation issues

NUM model Steady state Network as an Optimizer

Theorem (Low'2003)

Let
$$x^*, \lambda^*$$
 and set $y^*_a = \sum_{s \ni a} x^*_s$ and $q^*_s = \sum_{a \in s} \lambda^*_a$. Then:

$$\begin{array}{l} x_{s}^{*} = f_{s}(q_{s}^{*}) \\ \lambda_{a}^{*} = \psi_{a}(y_{a}^{*}) \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{l} x^{*} \text{ and } \lambda^{*} \text{ are optimal solutions} \\ \text{for } (P) \text{ and } (D) \text{ respectively} \end{array} \right.$$

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NUM model Steady state Network as an Optimizer

Usefulness?

- Reverse engineering of existing protocols
- Forward engineering of new protocols: $\mathit{f_s}$ and $\psi_{\textit{a}}$
- Conceive distributed algorithms to optimize prescribed utilities
- Flexible choice of congestion measure q_s
 - loss probability (TCP Reno/DropTail-RED-REM)
 - propagation delay (TCP Vegas of FAST)

Limitations?

- Delays in transmission of congestion prices
- Improper account of stochastic phenomena
- Single-path routing

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The model Optimization formulation

Markovian network utility maximization

- Want to design a distributed protocol that supports source congestion control and multi-path routing
- Goal: packet-level communication protocol that satisfies some prescribed optimality criteria at equilibrium
- Model based on the notion of Markovian traffic equilibrium

The model Optimization formulation

The Model

- Communication network G = (N, A)
- Source $s \in S$ sends packets from o_s to d_s at rate x_s
- Links have random prices $\tilde{\lambda}_{a} = \lambda_{a} + \epsilon_{a}$ with $\mathbb{E}(\epsilon_{a}) = 0$.

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At switch *i*, packets headed to destination *d* are routed through the link $a \in A_i^+$ that minimizes the cost to destination





Markov chain with transition matrix

$$P_{ij}^{d} = \begin{cases} \mathbb{P}(\tilde{z}_{a}^{d} \leq \tilde{z}_{b}^{d}, \forall b \in A_{i}^{+}) & \text{if } i = i_{a}, j = j_{a} \\ 0 & \text{otherwise} \end{cases}$$

At switch *i*, packets headed to destination *d* are routed through the link $a \in A_i^+$ that minimizes the cost to destination





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The model Optimization formulation

Example: Multinomial Logit routing

$$\tilde{z}_{a}^{d} = z_{a}^{d} - \epsilon_{a}^{d} \text{ with } \epsilon_{a}^{d} \text{ i.i.d. Gumbel} \Rightarrow$$

$$\mathbb{P}\left(\tilde{z}_{a}^{d} \leq \tilde{z}_{b}^{d}, \forall b \in A_{i}^{+}\right) = \frac{e^{-\beta z_{a}^{d}}}{\sum_{b \in A_{i}^{+}} e^{-\beta z_{b}^{d}}}.$$

Remark:

 $\begin{array}{lll} \beta \rightarrow 0 & \Leftrightarrow & {\rm random \ walk} \\ \beta \rightarrow \infty & \Leftrightarrow & {\rm shortest \ path} \end{array}$

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The model Optimization formulation

Expected flows

The flow ϕ_i^d entering node *i* and directed towards *d*

$$\phi_i^d = \sum_{\substack{o_s=i\\d_s=d}} x_s + \sum_{a \in A_i^-} v_a^d$$

splits among the outgoing links a = (i, j) according to

$$v_a^d = \phi_i^d P_{ij}^d$$



The model Optimization formulation

Expected costs

Letting
$$z_a^d = \mathbb{E}(\tilde{z}_a^d)$$
 and $q_i^d = \mathbb{E}(\tilde{q}_i^d)$, we have
 $z_a^d = \lambda_a + q_{j_a}^d$
 $q_i^d = \varphi_i^d(z^d)$

with

$$\varphi_i^d(z^d) \triangleq \mathbb{E}(\min_{a \in A_i^+}[z_a^d + \epsilon_a^d])$$

Moreover

$$\mathbb{P}\left(\tilde{z}_{a}^{d} \leq \tilde{z}_{b}^{d}, \forall b \in A_{i}^{+}\right) = \frac{\partial \varphi_{i}^{d}}{\partial z_{a}^{d}}(z^{d})$$

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The model Optimization formulation

Given rate control functions $f_s(\cdot)$ and congestion functions $\psi_a(\cdot)$.

Definition (Markovian NUM)

 (x, y, v, z, q, λ) is MNUM if $\lambda_a = \psi_a(y_a)$ and $q_s = f_s(x_s)$ with

$$y_a = \sum_d v_a^d$$
 (total flow on link *a*)
 $q_s = q_{o_s}^{d_s}$ (congestion price for source *s*)

where the expected costs (q, z) are such that

$$(ZQ) \quad \begin{cases} z_a^d = \lambda_a + q_{j_a}^d \\ q_i^d = \varphi_i^d(z^d) \end{cases}$$

and the expected flows v^d satisfy

$$(FC) \quad \begin{cases} \phi_i^d = \sum_{a \in A_i^{-} \\ d_s = d} x_s + \sum_{a \in A_i^{-}} v_a^d & \forall i \neq d \\ v_a^d = \phi_i^d \frac{\partial \varphi_i^d}{\partial z_a^d} (z^d) & \forall a \in A_i^+ \end{cases}$$

The model Optimization formulation

The dual problem

- (ZQ) defines z_a^d and q_i^d as implicit functions of λ
- then $x_s = f_s^{-1}(q_s(\lambda))$ yields x_s as function of λ
- (FC) then defines v_a^d as functions of λ

Thus: MNUM conditions $\Leftrightarrow \psi_a^{-1}(\lambda_a) = y_a = \sum_d v_a^d(\lambda)$

Theorem

 λ supports a MNUM iff it is an optimal solution of

$$(D) \quad \min_{\lambda} \quad \sum_{a \in A} \Psi_a^*(\lambda_a) + \sum_{s \in S} F_s^*(q_s(\lambda))$$

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The model Optimization formulation

The primal problem

Theorem

MNUM is the optimal solution of

$$\min_{(x,y,v)\in P}\sum_{s\in S}F_s(x_s) + \sum_{a\in A}\Psi_a(y_a) + \sum_{d\in D}\chi^d(v^d)$$

where

$$\chi^d(\mathbf{v}^d) = \sup_{z^d} \sum_{a \in A} (\varphi^d_{i_a}(z^d) - z^d_a) \mathbf{v}^d_a$$

and P is the polyhedron defined by flow conservation constraints.

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Implementation

- Implement a distributed algorithm for the previous model
- Protocol with 2 time-scales: a slow one for choosing prices, and a faster one for rate control and price estimation for users
- Notification between routers using a RIP protocol, changing the measure of distance (number of hops) for link prices. This enables dynamic routing.
- Communicate prices to users. Routers can communicate the prices to the links, but at a slower time-scale than rate control.

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Price estimation for sources

- Use Explicit Congestion Notification (ECN)
- Assume that prices take values between 0 and 1
- Adapt Adler *et al.* to estimate end-to-end prices $q_s = q_{o_s}^{d_s}$

ECN: Markov chain for marking with $X_0 = 0$ and transitions

$$X_i = \begin{cases} X_{i-1} & \frac{i-1}{i} \\ 1 & \frac{\lambda_{a_i}}{i} \\ 0 & \frac{1-\lambda_{a_i}}{i} \end{cases}$$

- For fixed route $\mathbb{E}(X_k) = \frac{1}{k} \sum_{i=1}^k \lambda_{a_i}$
- Knowing the route length k we can estimate end-to-end price
- Routers need their position *i* in the route for the pbb
- Markovian case: unknown length of routes and positions

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ECN with Markovian route choice

$$\mathbb{E}(X^{s}) = \sum_{r \in R^{s}} \left(\prod_{a \in r} p_{i_{a}j_{a}} \right) \left(\frac{1}{|r|} \sum_{a \in r} \lambda_{a} \right),$$

and

$$q^{s} = \sum_{r \in R^{s}} \left(\prod_{a \in r} p_{i_{a}j_{a}} \right) \left(\sum_{a \in r} \lambda_{a} \right).$$

If we correct the factor 1/|r| we get an unbiased estimator of q^s using sample averages.

Modify the Markov chain using the TTL (time-to-live) value on the IP header. As the TTL value is decreasing, we define a Markov chain X^s with $X_0^s = 0$ and

$$X_{i}^{s} = \begin{cases} X_{i-1}^{s} & \frac{T_{i}}{T_{i-1}} \\ 1 & \frac{T_{i}}{M} \lambda_{a_{i}} \\ 0 & 1 - T_{i} \left[\frac{1}{T_{i-1}} + \frac{\lambda_{a_{i}}}{M} \right]. \end{cases}$$

Where M is an upper bound for the square of all TTL values (this makes that the three transitions have positive probability).

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If the final TTL value is T then

$$\mathbb{E}(X^{s}) = \sum_{r \in R^{s}} \left(\prod_{a \in r} p_{i_{a}j_{a}} \right) \left(\frac{T}{M} \sum_{a \in r} \lambda_{a} \right)$$

and we get an unbiased estimator for q^s

$$Y^s = \frac{M}{T}X^s$$

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Conclusions

- We proposed a model that considers multipath routing for NUM, inspired in a packet-level dynamics
- Communication of variables required by protocol is possible under current TCP/IP
- ECN yields unbiased estimation of prices for users, that work on the same time-scale as rate control

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Future work

- Design a distributed algorithm for the model
- Study stochastic stability of the markovian equilibrium
- Find a ECN mechanism that works for unbounded prices
- Analyze MNUM when randomness tends to 0

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